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5.04 Principles of Inorganic Chemistry II
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Lecture 3: Irreducible Representations and Character Tables

Similarity transformations yield **irreducible representations**, Γ_i , which lead to the useful tool in group theory – the **character table**. The general strategy for determining Γ_i is as follows: **A**, **B** and **C** are matrix representations of symmetry operations of an arbitrary basis set (i.e., elements on which symmetry operations are performed). There is some similarity transform operator ν such that

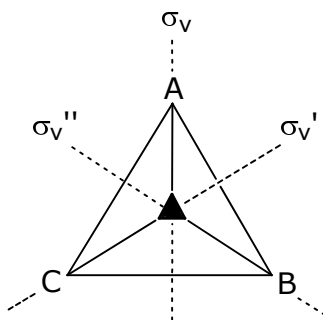
$$\begin{aligned}\mathbf{A}' &= \nu^{-1} \cdot \mathbf{A} \cdot \nu \\ \mathbf{B}' &= \nu^{-1} \cdot \mathbf{B} \cdot \nu \\ \mathbf{C}' &= \nu^{-1} \cdot \mathbf{C} \cdot \nu\end{aligned}$$

where ν uniquely produces **block-diagonalized** matrices, which are matrices possessing square arrays along the diagonal and zeros outside the blocks

$$\mathbf{A}' = \begin{bmatrix} \boxed{A_1} & & \\ & \boxed{A_2} & \\ & & \boxed{A_3} \end{bmatrix} \quad \mathbf{B}' = \begin{bmatrix} \boxed{B_1} & & \\ & \boxed{B_2} & \\ & & \boxed{B_3} \end{bmatrix} \quad \mathbf{C}' = \begin{bmatrix} \boxed{C_1} & & \\ & \boxed{C_2} & \\ & & \boxed{C_3} \end{bmatrix}$$

Matrices **A**, **B**, and **C** are **reducible**. Sub-matrices A_i , B_i and C_i obey the same multiplication properties as **A**, **B** and **C**. If application of the similarity transform does not further block-diagonalize **A'**, **B'** and **C'**, then the blocks are **irreducible representations**. The **character** is the sum of the diagonal elements of Γ_i .

As an example, let's continue with our exemplary group: $E, C_3, C_3^2, \sigma_v, \sigma_v', \sigma_v''$ by defining an arbitrary basis ... a triangle



The basis set is described by the triangles vertices, points A, B and C. The transformation properties of these points under the symmetry operations of the group are:

$$E \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix} \quad \sigma_V \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} A \\ C \\ B \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

$$C_3 \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} B \\ C \\ A \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix} \quad \sigma_V' \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} B \\ A \\ C \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

$$C_3^2 \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} C \\ A \\ B \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix} \quad \sigma_V'' \begin{bmatrix} A \\ B \\ C \end{bmatrix} = \begin{bmatrix} C \\ B \\ A \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

These matrices are not block-diagonalized, however a suitable similarity transformation will accomplish the task,

$$v = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} & 0 \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \end{bmatrix} ; \quad v^{-1} = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

Applying the similarity transformation with C_3 as the example,

$$v^{-1} \cdot C_3 \cdot v = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} & 0 \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix} = C_3^*$$

if $\gamma^{-1} \cdot \mathbf{C}_3^* \cdot \gamma$ is applied again, the matrix is not block diagonalized any further. The same diagonal sum is obtained (though off-diagonal elements may change). In this case, \mathbf{C}_3^* is an irreducible representation, Γ_i .

The similarity transformation applied to other reducible representations yields:

$$\gamma^{-1} \cdot \mathbf{E} \cdot \gamma = \mathbf{E}^* = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \gamma^{-1} \cdot \mathbf{C}_3^2 \cdot \gamma = \mathbf{C}_3^{2*} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$$

$$\gamma^{-1} \cdot \sigma_v \cdot \gamma = \sigma_v^* = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \gamma^{-1} \cdot \sigma_v'' \cdot \gamma = \sigma_v^{''*} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$\gamma^{-1} \cdot \sigma_v' \cdot \gamma = \sigma_v'^* = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

As above, the block-diagonalized matrices do not further reduce under re-application of the similarity transform. All are Γ_{irrs} .

Thus a 3×3 reducible representation, Γ_{red} , has been decomposed under a similarity transformation into a $1 (1 \times 1)$ and $1 (2 \times 2)$ block-diagonalized irreducible representations, Γ_i . The traces (i.e. sum of diagonal matrix elements) of the Γ_i 's under each operation yield the **characters** (indicated by χ) of the representation. Taking the traces of each of the blocks:

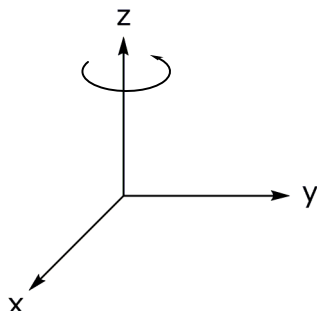
	E	C_3	C_3^2	σ_v	σ_v'	σ_v''
Γ_1	1	1	1	1	1	1
Γ_2	2	-1	-1	0	0	0

	E	$2C_3$	$3\sigma_v$
Γ_1	1	1	1
Γ_2	2	-1	0

Note: characters of operators in the same class are identical

This collection of characters for a given irreducible representation, under the operations of a group is called a **character table**. As this example shows, from a completely arbitrary basis and a similarity transform, a character table is born.

The triangular basis set does not uncover all Γ_{irr} of the group defined by $\{E, C_3, C_3^2, \sigma_v, \sigma_v', \sigma_v''\}$. A triangle represents Cartesian coordinate space (x,y,z) for which the Γ_i s were determined. May choose other basis functions in an attempt to uncover other Γ_i s. For instance, consider a rotation about the z-axis,



The transformation properties of this basis function, R_z , under the operations of the group (will choose only 1 operation from each class, since characters of operators in a class are identical):

$$E: R_z \rightarrow R_z$$

$$C_3: R_z \rightarrow R_z$$

$$\sigma_v(xy): R_z \rightarrow \bar{R}_z$$

Note, these transformation properties give rise to a Γ_i that is not contained in a triangular basis. A new (1×1) basis is obtained, Γ_3 , which describes the transform properties for R_z . A summary of the Γ_i for the group defined by $E, C_3, C_3^2, \sigma_v, \sigma_v', \sigma_v''$ is:

	E	$2C_3$	$3\sigma_v$	
Γ_1	1	1	1	} from triangular basis, i.e. (x, y, z)
Γ_2	2	-1	0	
Γ_3	1	1	-1	

Is this character table complete? Irreducible representations and their characters obey certain algebraic relationships. From these 5 rules, we can ascertain whether this is a complete character table for these 6 symmetry operations.

Five important rules govern irreducible representations and their characters:

Rule 1

The sum of the squares of the dimensions, l , of irreducible representation Γ_i is equal to the order, h , of the group,

$$\sum_i l_i^2 = l_1^2 + l_2^2 + l_3^2 + \dots = h$$

↘ order of matrix representation of Γ_i (e.g. $l = 2$ for a 2×2)

Since the character under the identity operation is equal to the dimension of Γ_i (since E is always the unit matrix), the rule can be reformulated as,

$$\sum_i [x_i(E)]^2 = h$$

↘ character under E

Rule 2

The sum of squares of the characters of irreducible representation Γ_i equals h

$$\sum_R [x_i(R)]^2 = h$$

↘ character of Γ_i under operation R

Rule 3

Vectors whose components are characters of two different irreducible representations are orthogonal

$$\sum_R [x_i(R)][x_j(R)] = 0 \quad \text{for } i \neq j$$

Rule 4

For a given representation, characters of all matrices belonging to operations in the same class are identical

Rule 5

The number of Γ_i s of a group is equal to the number of classes in a group.

With these rules one can algebraically construct a character table. Returning to our example, let's construct the character table in the absence of an arbitrary basis:

Rule 5: $E (C_3, C_3^2) (\sigma_v, \sigma_v', \sigma_v'') \dots 3 \text{ classes} \therefore 3 \Gamma_i$ s

Rule 1: $l_1^2 + l_2^2 + l_3^2 = 6 \therefore l_1 = l_2 = 1, l_3 = 2$

Rule 2: All character tables have a totally symmetric representation. Thus one of the irreducible representations, Γ_i , possesses the character set $\chi_1(E) = 1$, $\chi_1(C_3, C_3^2) = 1$, $\chi_1(\sigma_v, \sigma_v', \sigma_v'') = 1$. Applying Rule 2, we find for the other irreducible representation of dimension 1,

$$1 \cdot \chi_1(E) \cdot \chi_2(E) + 2 \cdot \chi_1(C_3) \cdot \chi_2(C_3) + 3 \cdot \chi_1(\sigma_v) \cdot \chi_2(\sigma_v) = 0$$

consequence of Rule 4

$$1 \cdot 1 \cdot \chi_2(E) + 2 \cdot 1 \cdot \chi_2(C_3) + 3 \cdot 1 \cdot \chi_2(\sigma_v) = 0$$

Since $\chi_2(E) = 1$,

$$1 + 2 \cdot \chi_2(C_3) + 3 \cdot \chi_2(\sigma_v) = 0 \therefore \chi_2(C_3) = 1, \chi_2(\sigma_v) = -1$$

For the case of $\Gamma_3 (l_3 = 2)$ there is not a unique solution to Rule 2

$$2 + 2 \cdot \chi_3(C_3) + 3 \cdot \chi_3(\sigma_v) = 0$$

However, application of Rule 2 to Γ_3 gives us one equation for two unknowns. Have several options to obtain a second independent equation:

$$\text{Rule 1: } 1 \cdot 2^2 + 2[\chi_3(C_3)]^2 + 3[\chi_3(\sigma_v)]^2 = 6$$

$$\text{Rule 3: } 1 \cdot 1 \cdot 2 + 2 \cdot 1 \cdot \chi_3(C_3) + 3 \cdot 1 \cdot \chi_3(\sigma_v) = 0$$

or

$$1 \cdot 1 \cdot 2 + 2 \cdot 1 \cdot \chi_3(C_3) + 3 \cdot (-1) \cdot \chi_3(\sigma_v) = 0$$

Solving simultaneously yields $\chi_3(C_3) = -1, \chi_3(\sigma_v) = 0$

Thus the same result shown on pg 4 is obtained:

	E	$2C_3$	$3\sigma_v$
Γ_1	1	1	1
Γ_2	2	-1	0
Γ_3	1	1	-1

