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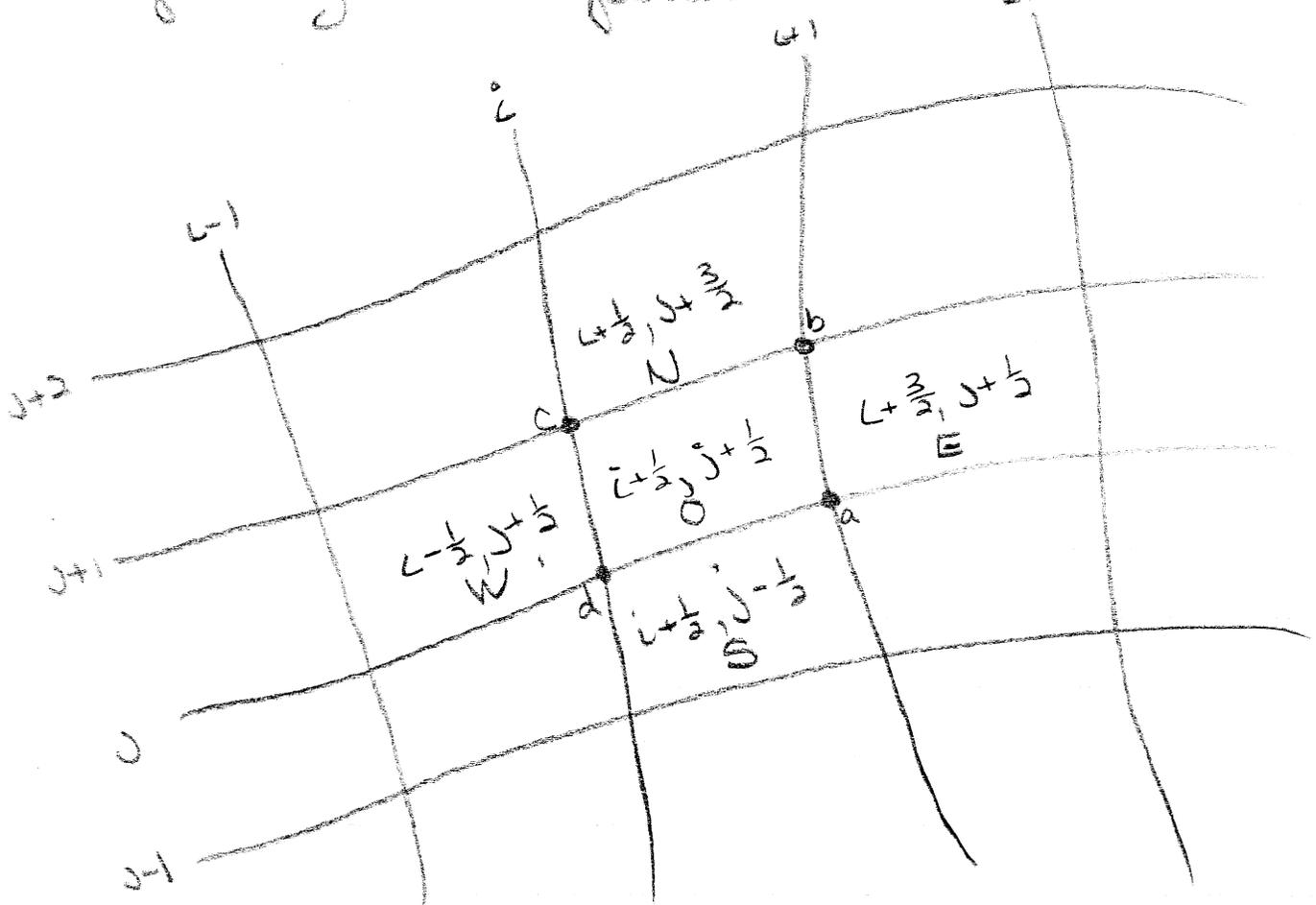
16.901 Notes for March 15, 2002

- * Finite Volume schemes in multiple dimensions
- * Unstructured vs. structured grids

Let's return to the energy equation without diffusion in multiple dimensions:

$$\iiint_V \frac{\partial E}{\partial t} dV + \oiint_S E \vec{\sigma} \cdot \vec{n} dS = 0$$

Suppose we have a non-uniform though logically rectangular mesh:



As in 1-D, define a cell-average state:

$$E_{i+\frac{1}{2}, j+\frac{1}{2}} \equiv \frac{1}{A_{i+\frac{1}{2}, j+\frac{1}{2}}} \iint_{A_{i+\frac{1}{2}, j+\frac{1}{2}}} E \, dA$$

where $A_{i+\frac{1}{2}, j+\frac{1}{2}}$ = cell area of $i+\frac{1}{2}, j+\frac{1}{2}$

The conservation law applied to $A_{i+\frac{1}{2}, j+\frac{1}{2}}$ is:

$$A_{i+\frac{1}{2}, j+\frac{1}{2}} \frac{dE_{i+\frac{1}{2}, j+\frac{1}{2}}}{dt} + \int_a^b E \vec{v} \cdot \vec{n} \, ds + \int_b^c E \vec{v} \cdot \vec{n} \, ds + \int_c^d E \vec{v} \cdot \vec{n} \, ds + \int_d^a E \vec{v} \cdot \vec{n} \, ds = 0$$

The next issue is to evaluate the line integrals of the fluxes on each face. Some options:

Average: $\int_a^b E \vec{v} \cdot \vec{n} \, ds \approx \frac{1}{\Delta s} \left[(E \vec{v})_E + (E \vec{v})_O \right] \cdot \vec{n}_{ab} \Delta s_{ab}$

Δs_{ab} face length
 \vec{n}_{ab} face unit normal

This produces a central difference approximation

$$\begin{aligned}
 & A_{i+\frac{1}{2}, j+\frac{1}{2}} \frac{dE_{i,j+\frac{1}{2}}}{dt} + \frac{1}{2} (E\vec{v})_0 \cdot \left[\vec{n}_{ab} \Delta S_{ab} + \vec{n}_{bc} \Delta S_{bc} + \vec{n}_{cd} \Delta S_{cd} + \vec{n}_{da} \Delta S_{da} \right] \\
 & + \frac{1}{2} (E\vec{v})_E \cdot \vec{n}_{ab} \Delta S_{ab} + \frac{1}{2} (E\vec{v})_W \cdot \vec{n}_{bc} \Delta S_{bc} \\
 & + \frac{1}{2} (E\vec{v})_S \cdot \vec{n}_{cd} \Delta S_{cd} + \frac{1}{2} (E\vec{v})_N \cdot \vec{n}_{da} \Delta S_{da} = 0
 \end{aligned}$$

= 0 for closed cell

⇒ No dependence on $E_0 = E_{i+\frac{1}{2}, j+\frac{1}{2}}$ through flux term! ⇒ Central difference!

We can also implement an upwind scheme as follows:

For edge ab: if $\vec{v}_{ab} \cdot \vec{n}_{ab} > 0$ then

$$\int_a^b E\vec{v} \cdot \vec{n} ds \cong E_0 \vec{v}_{ab} \cdot \vec{n}_{ab} \Delta S_{ab}$$

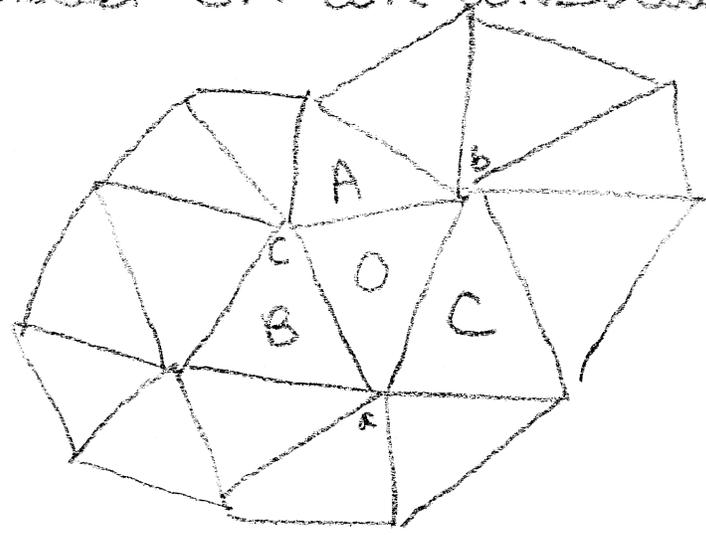
if $\vec{v}_{ab} \cdot \vec{n}_{ab} < 0$ then

$$\int_a^b E\vec{v} \cdot \vec{n} ds \cong E_E \vec{v}_{ab} \cdot \vec{n}_{ab} \Delta S_{ab}$$

Or, more compactly:

$$\int_a^b E\vec{v} \cdot \vec{n} ds = \left\{ \frac{1}{2} (E_E + E_0) \vec{v}_{ab} \cdot \vec{n}_{ab} - \frac{1}{2} (E_E - E_0) |\vec{v}_{ab} \cdot \vec{n}_{ab}| \right\} \Delta S_{ab}$$

This finite volume scheme can also be implemented on an "unstructured" mesh:



In this case, the finite volume method for cell O is:

$$A_0 \frac{dE_0}{dt} + \int_a^b E \vec{\sigma} \cdot \vec{n} ds + \int_b^c E \vec{\sigma} \cdot \vec{n} ds + \int_c^a E \vec{\sigma} \cdot \vec{n} ds = C$$

As before, we need to evaluate the flux integrals & derivative in time.

Why would unstructured meshes be used

- * better suited for complex geometry
- * can adapt to local features

Why would structured meshes be used?

* require less computer memory than unstructured
(unstructured mesh must store connectivity info)

* structured equations can generally be solved with techniques that take advantage of structure
⇒ faster solutions