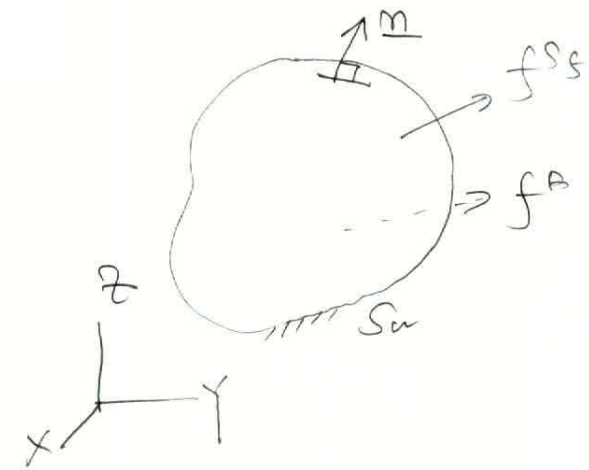


## Finite element formulation - an example.

(18)



$$(1) \begin{cases} \tau_{ij,j} + f_i^B = 0 & \text{in } V \\ \tau_{ij} n_j = f_i^{S_f} & \text{on } S_f \\ u_i|_{S_u} = 0 & \text{on } S_u \end{cases}$$

Recall we set for the moment

$$S = S_f, S_u = \emptyset$$

$$(2) \quad \underline{K} \underline{U} = \underline{R}$$

$$\underline{K} = \sum_m \underline{K}^{(m)}, \quad K^{(m)} = \int \underline{B}^{(m)T} \underline{C}^{(m)} \underline{B}^{(m)} dV^{(m)}$$

$$\underline{R} = \underline{R}_B + \underline{R}_S, \quad \underline{R}_B = \sum \underline{R}_B^{(m)}; \quad \underline{R}_S = \sum \underline{R}_S^{(m)}$$

$$\underline{R}_B^{(m)} = \int H^{(m)T} f^{B(m)} dV^{(m)}$$

$$\underline{R}_S^{(m)} = \int H^{S(m)T} f^{S(m)} dS^{(m)}$$

$S^{(m)}$  = all external surface of element (m)

The key assumption.

$$\underline{u}^{(m)} = \underline{H}^{(m)} \underline{u} \quad (A)$$

↓

$$\underline{\epsilon}^{(m)} = \underline{B}^{(m)} \underline{u} \quad (B)$$

# In dynamic analysis

$$f^{B(m)} = \tilde{f}^{B(m)} - \rho^{(m)} \ddot{u}^{(m)} = \tilde{f}^{B(m)} \quad \begin{matrix} \text{all body forces} \\ \text{excluding} \\ \text{inertia force} \end{matrix}$$

Using (A)

$$\ddot{u}^{(m)} = H^{(m)} \ddot{u} \quad (C)$$

Eq (2) now becomes

$$K \underline{U} = \underline{R} - \left[ \sum_m \int H^{(m)T} \rho^{(m)} H^{(m)} dV^{(m)} \right] \ddot{\underline{u}}$$

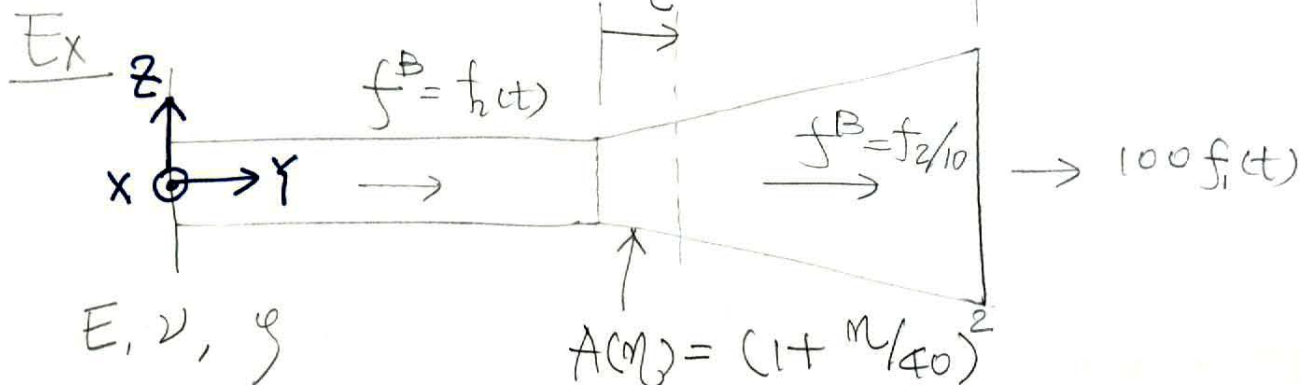
where  $\underline{R}$  is

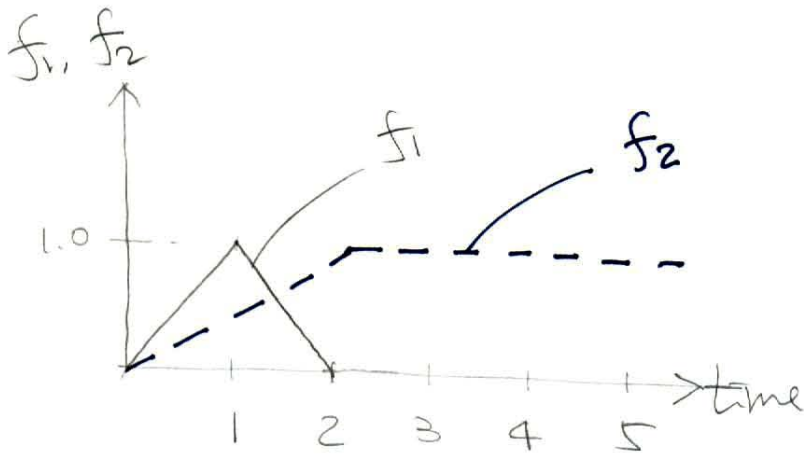
constructed using  $\tilde{f}^{B(m)}$  &  $f^{S(m)}$

$$\underline{M} \ddot{\underline{U}} + \underline{K} \underline{U} = \underline{R} \quad ; \quad \underline{M} = \sum_m \underline{M}^{(m)} = \underline{M}^{(m)} = \int H^{(m)T} \rho^{(m)} H^{(m)} dV^{(m)}$$

Similarly, we could attempt to include damping forces

$$f^{B(m)} = \tilde{f}^{B(m)} - \rho^{(m)} \ddot{u}^{(m)} - \underbrace{c^{(m)} \dot{u}^{(m)}}_{\text{element property}} = \tilde{f}^{B(m)} - \rho^{(m)} \ddot{u}^{(m)} - c^{(m)} \dot{u}^{(m)} = H^{(m)} \ddot{u} + c^{(m)} \dot{u} + \tilde{f}^{B(m)}$$





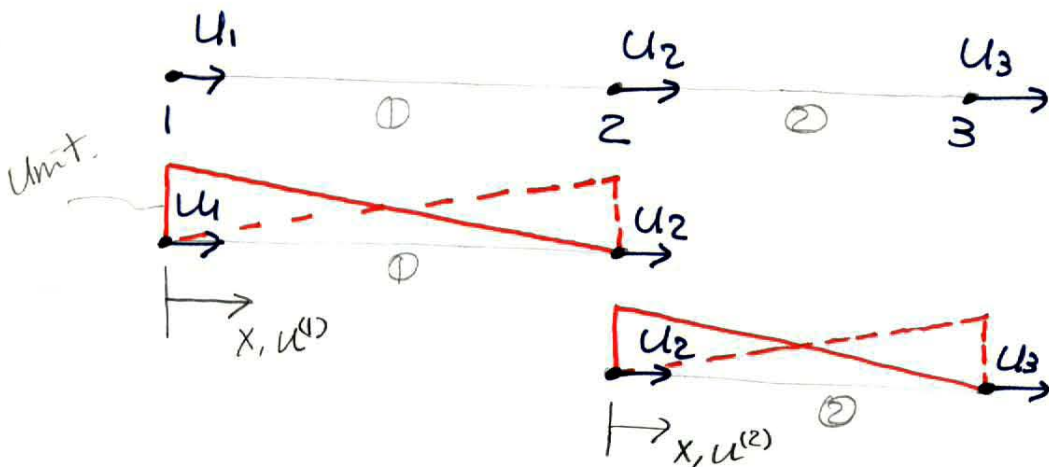
Math Model

Eg (1):

$$\frac{\partial}{\partial x} \left( EA \frac{\partial v}{\partial y} \right) = -f^B A$$

$$EA \frac{\partial v}{\partial y} \Big|_{y=180} = 100 f_1$$

$$v \Big|_{y=0} = 0$$



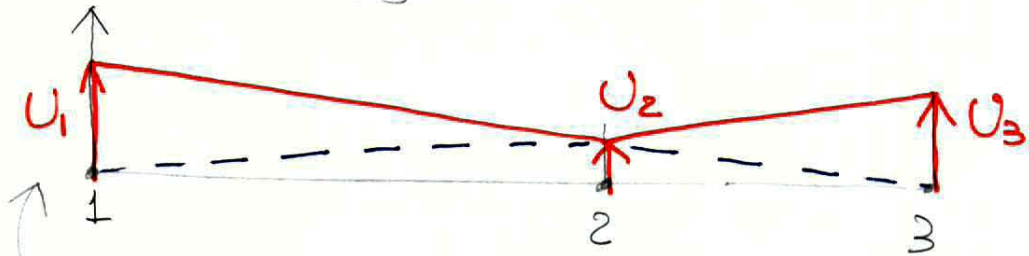
$$u^{(1)}(x) = \underbrace{\begin{bmatrix} 1 - \frac{x}{100} & \frac{x}{100} & 0 \end{bmatrix}}_{H^{(1)}} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

↑  
u<sub>3</sub> doesn't affect

$$\ddot{u}^{(1)}(x,t) = \begin{bmatrix} 1 - \frac{x}{100} & \frac{x}{100} & 0 \end{bmatrix} \begin{bmatrix} \ddot{u}_1 \\ \ddot{u}_2 \\ \ddot{u}_3 \end{bmatrix}$$

$$\underline{u}^{(2)} = \begin{bmatrix} 0 & 1 - \frac{x}{80} & \frac{x}{80} \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix} \quad (2)$$

Note: The displ in the structure are assumed as



In this problem, we set as 0

$$\ddot{u}^{(2)} = H^{(2)} \ddot{u}$$

$$\underline{\varepsilon}^{(1)} = \varepsilon_{xx}^{(1)} = \frac{\partial u^{(1)}}{\partial x} = \begin{bmatrix} -\frac{1}{100} & \frac{1}{100} & 0 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix}$$

$$\underline{\varepsilon}^{(2)} = \varepsilon_{xx}^{(2)} = \frac{\partial u^{(2)}}{\partial x} = \begin{bmatrix} 0 & -\frac{1}{80} & \frac{1}{80} \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix}$$

$$\underline{K} = \underline{K}^{(1)} + \underline{K}^{(2)} = \int_0^{100} (1) E \begin{bmatrix} -\frac{1}{100} \\ \frac{1}{100} \\ 0 \end{bmatrix} \begin{bmatrix} -\frac{1}{100} & \frac{1}{100} & 0 \end{bmatrix} dx$$

$$+ \int_0^{80} E \left(1 + \frac{x}{40}\right)^2 \begin{bmatrix} 0 \\ -\frac{1}{80} \\ \frac{1}{80} \end{bmatrix} \begin{bmatrix} 0 & -\frac{1}{80} & \frac{1}{80} \end{bmatrix} dx$$

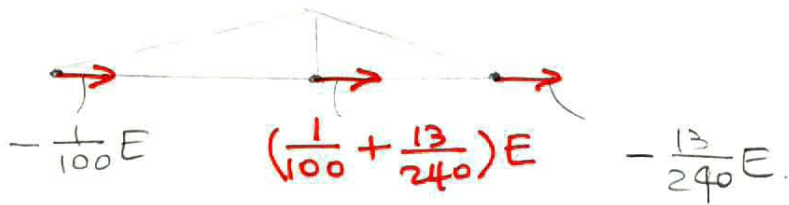
$$\underline{K} = \frac{E \cdot 1}{100} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \frac{13E}{240} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$1 < 9$   
 make sense

$\frac{13}{3} \frac{E}{80} \leftarrow \frac{EA^*}{L} = A^* = \frac{13}{3}$

$$\underline{K} = E \begin{bmatrix} \frac{1}{100} & -\frac{1}{100} & 0 \\ -\frac{1}{100} & \frac{1}{100} + \frac{13}{240} & -\frac{13}{240} \\ 0 & -\frac{13}{240} & \frac{13}{240} \end{bmatrix}; \text{ Column Sum will be 0}$$

Assume  $u_1 = 0, u_2 = 1, u_3 = 0$



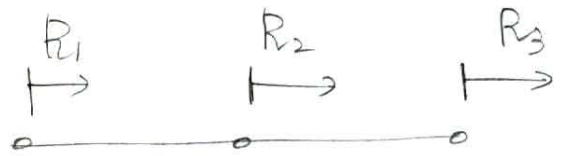
$$\underline{R}_D = (1) \int_0^{100} \underline{H}^{(1)T} \underline{f}^{(1)} dx + \int_0^{80} \underline{H}^{(2)T} \underline{f}^{(2)} \underbrace{\left(1 + \frac{x}{80}\right)^2}_{dV} dx$$

$$\underline{R}_S = \begin{bmatrix} 0 \\ 0 \\ 100f_1 \end{bmatrix} \equiv \underline{R}^{S(2)} = \int_{S^{(2)}} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \frac{100f_1(t)}{9} dS \Big|_{x=80}$$

$$\underline{K} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \underline{R}$$

Singular, we cannot solve.

impose  $u_1 = 0$



Rigid body Motion.

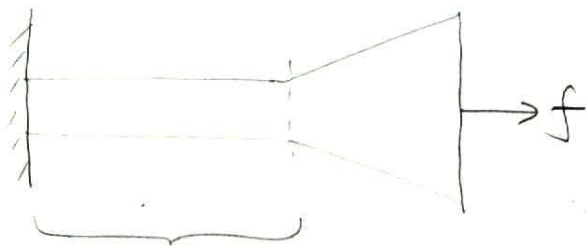
$$E \begin{bmatrix} \frac{1}{100} + \frac{13}{240} & -\frac{13}{240} \\ -\frac{13}{240} & \frac{13}{240} \end{bmatrix} \begin{pmatrix} U_2 \\ U_3 \end{pmatrix} = \begin{pmatrix} R_2 \\ R_3 \end{pmatrix}$$

Now calculate  $U_2, U_3$ , ( $U_1=0$ ) and obtain

$$\tau_{xx}^{(1)} = E \cdot \underline{B}^{(1)} \underline{U}$$

$$\tau_{xx}^{(2)} = E \cdot \underline{B}^{(2)} \underline{U}$$

Real stress is quadratic, so the FEM sol is not exact.



In this case, we will get exact solution.