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Introduction

Unmanned and Autonomous Systems of Systems (UASoS) have become increasingly complex and bring interesting challenges to testing and evaluation. Currently no traditional testing techniques or programs of record exist.

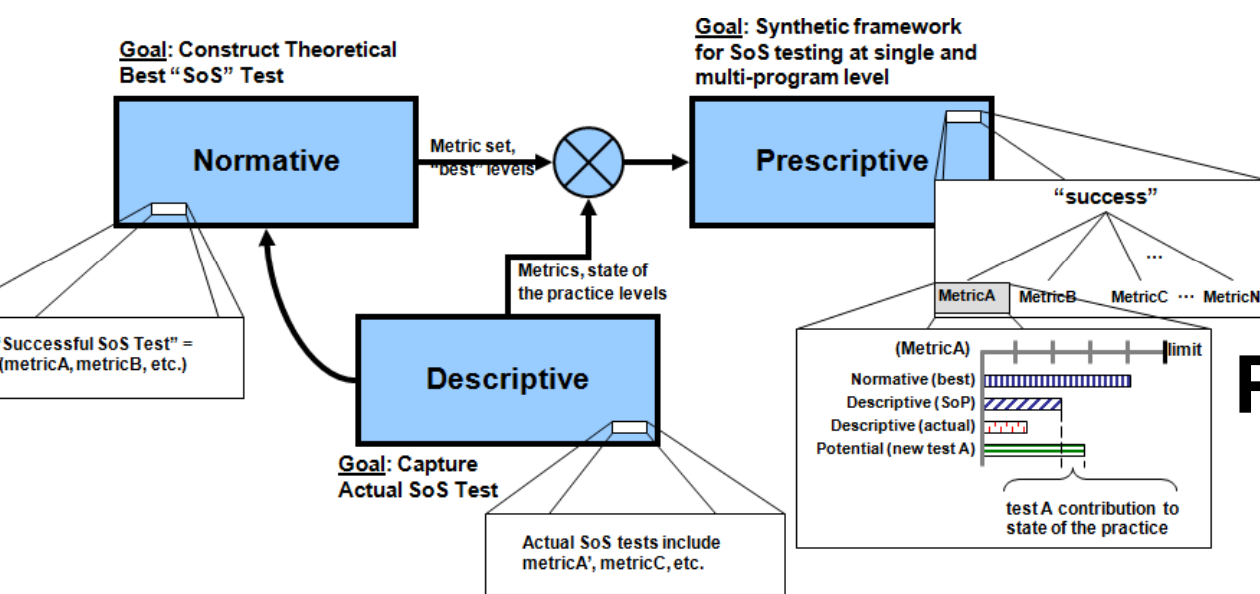
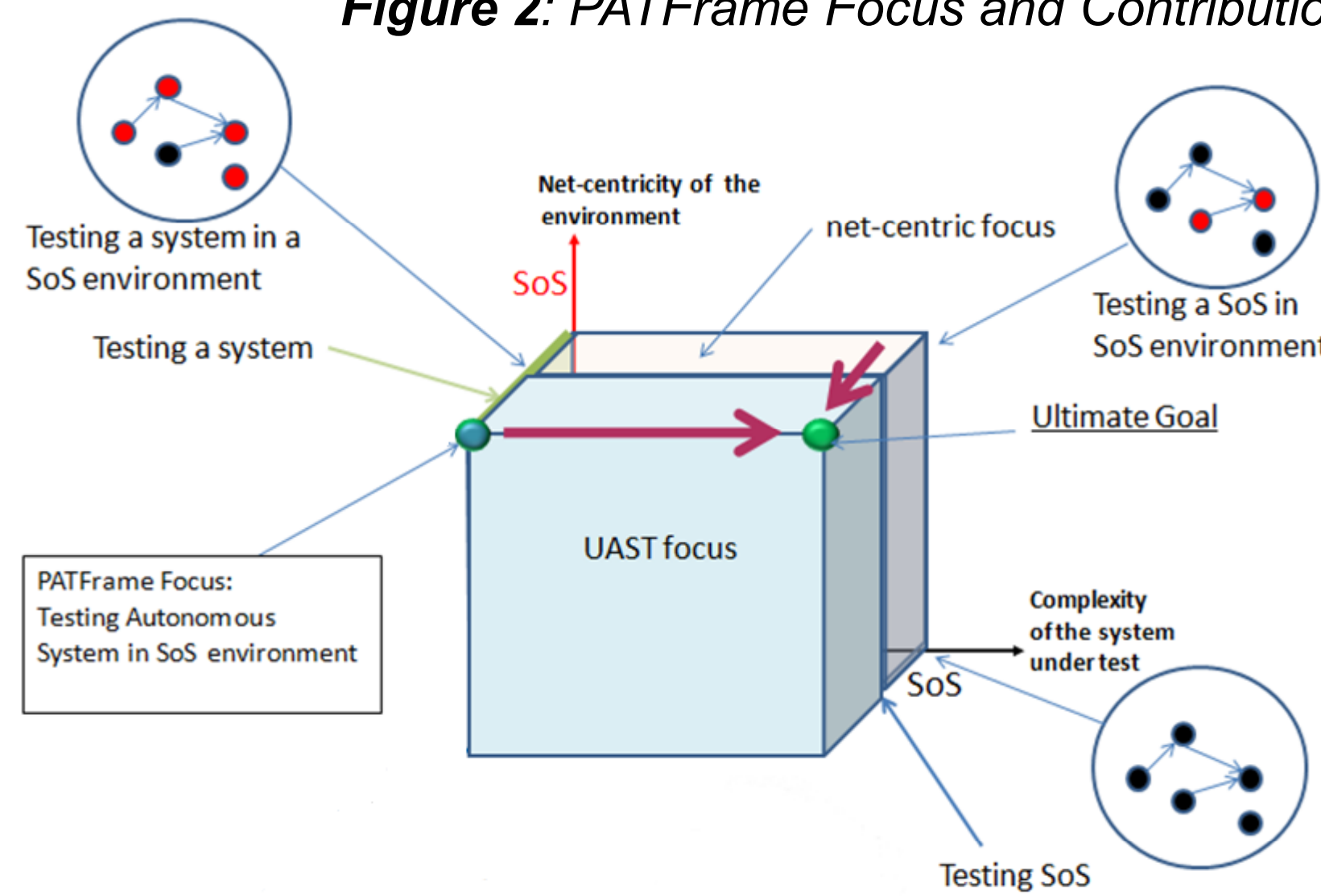


Figure 1: PATFrame Approach

To ensure UASoS are effective, safe, suitable and survivable the **Prescriptive and Adaptive Testing Framework** for UASoS is being created.

Problem Focus

Figure 2: PATFrame Focus and Contributions



Problem Statement

Current T&E processes lack the ability to determine the effort required for testing UASoS. The questions arises, "When am I done testing?" We hypothesize that the effort required for testing is directly related to the risks as well as technical and organizational cost drivers, which influence the testing and evaluation process. By using a risk based testing and cost model approach we seek to answer this question to determine the ultimate test stop point.

Current Work

Literature review Case Studies Interviews Surveys

SPHERES Case Study

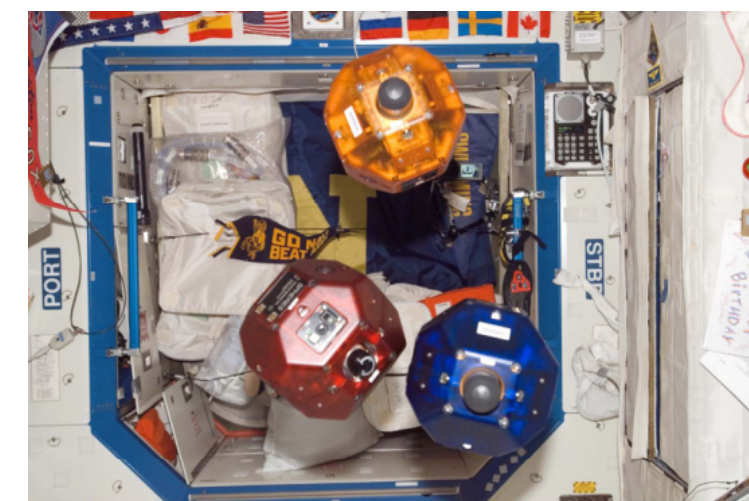


Figure 3: SPHERES at International Space Station

The **Synchronized Position Hold Engage Reorient Experimental Satellites** testbed serves a dual role as both a risk mitigation unit and distributed satellite system of systems

Principles of Risk Mitigation

- Modularity
- Requirements Balance
- Enabling field of study
- Iterative Research
- Incremental Technology Maturation
- Optimized utilization of Resources

Future Work



...continue knowledge acquisition to minimize risk by developing PATFrame as a decision support system for testing and evaluating UASoS

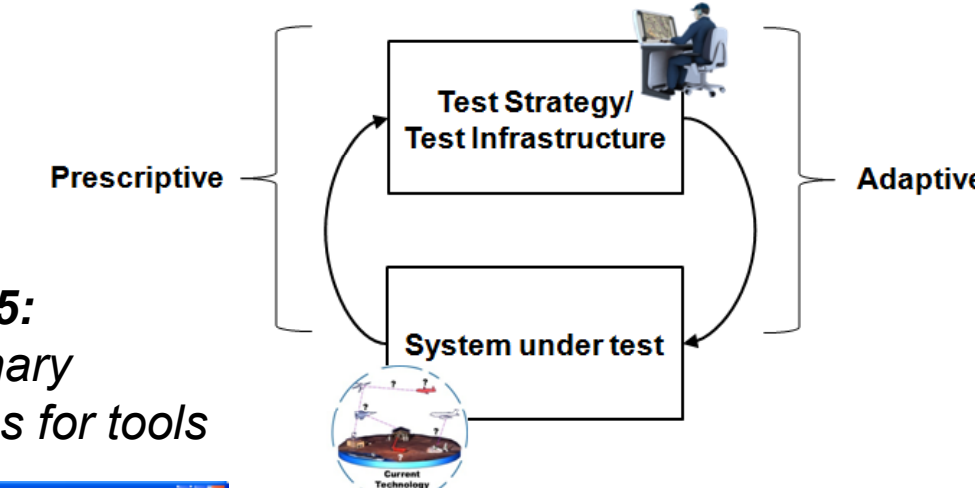
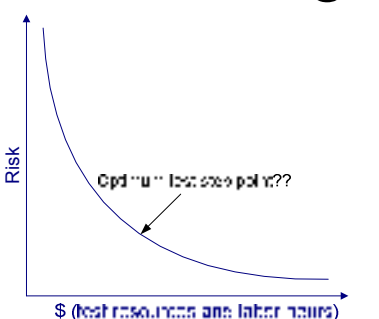


Figure 5: Preliminary mockups for tools

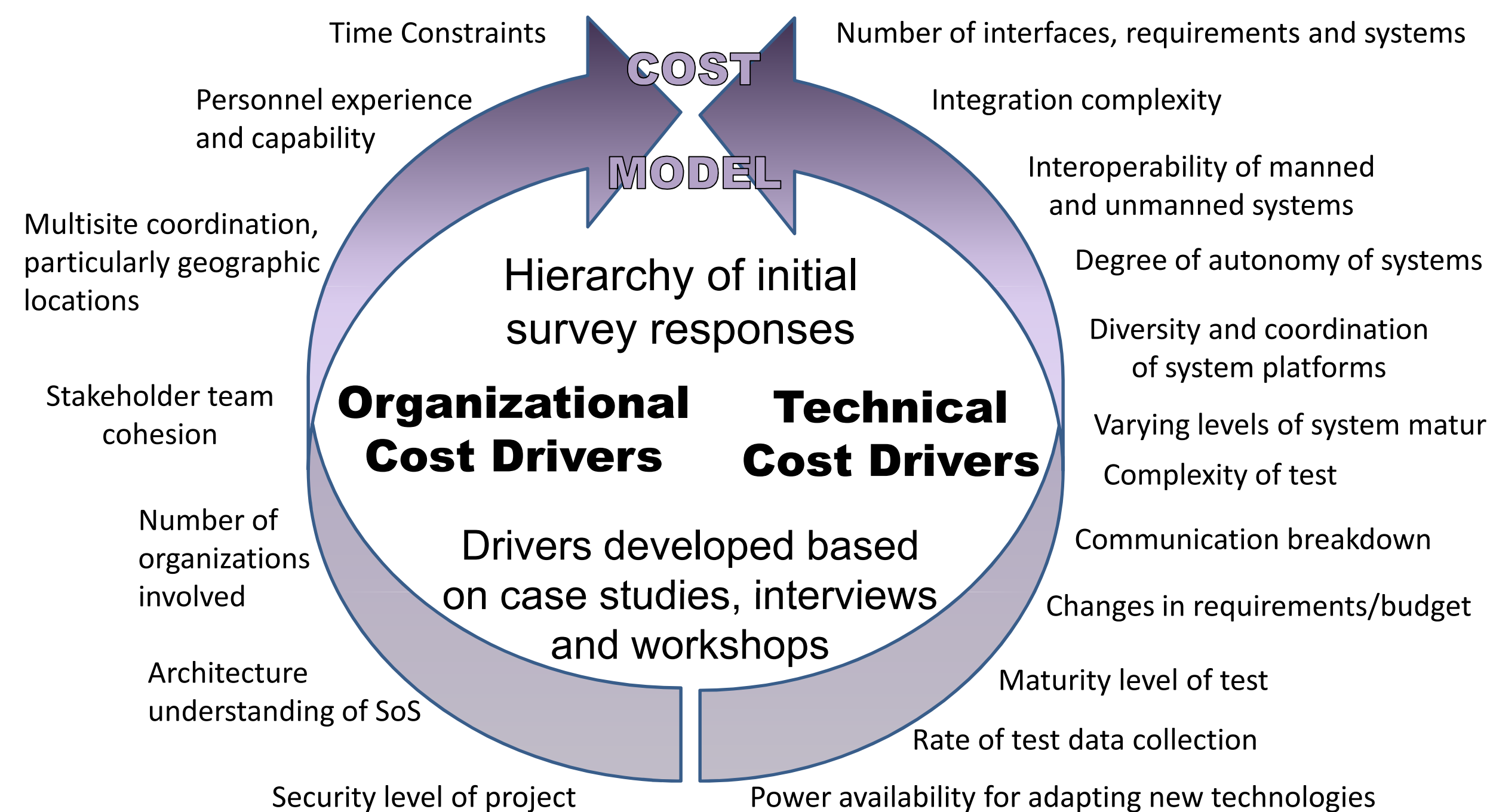
...use both qualitative data from subject matter experts and quantitative data from test projects to validate inputs and ultimate stop point for testing



...develop the inputs for a tool to be used by test planners and testers to determine the effort required for testing

...include parameters that will calculate the probability of accomplishing a task in given resources and test cost driver inputs

Initial Technical and Organizational Cost Drivers



Acknowledgements

Sponsors

Transition Partners

Collaborators

